



Keynote Talk @ DRCN

Coimbra, Portugal
March 20th 2019



POLITECNICO DI MILANO

15th International Conference

Design of Reliable
Communication Networks

March 19-21, 2019
Coimbra, Portugal



Reliable Optical Metro Networks for 5G communications

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WG2 Leader
Cost Action RECODIS

RECODIS
Resilient communication services
protecting end-user applications
from disaster-based failures




@MaxTornatore



Reduce latency to milliseconds 


Instant response

Ensure up to 6 nine's service availability 

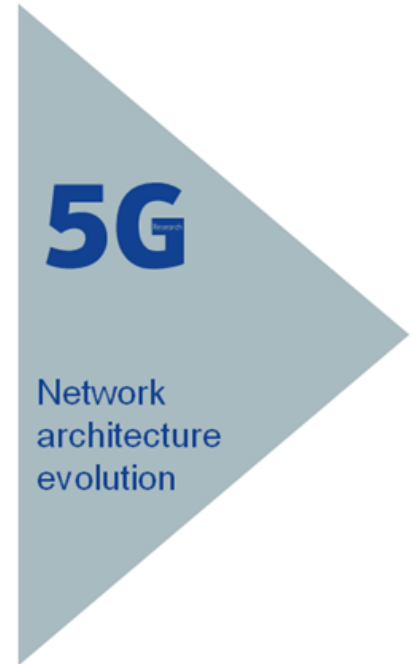
Survivability

Support up to 1000 times more capacity 

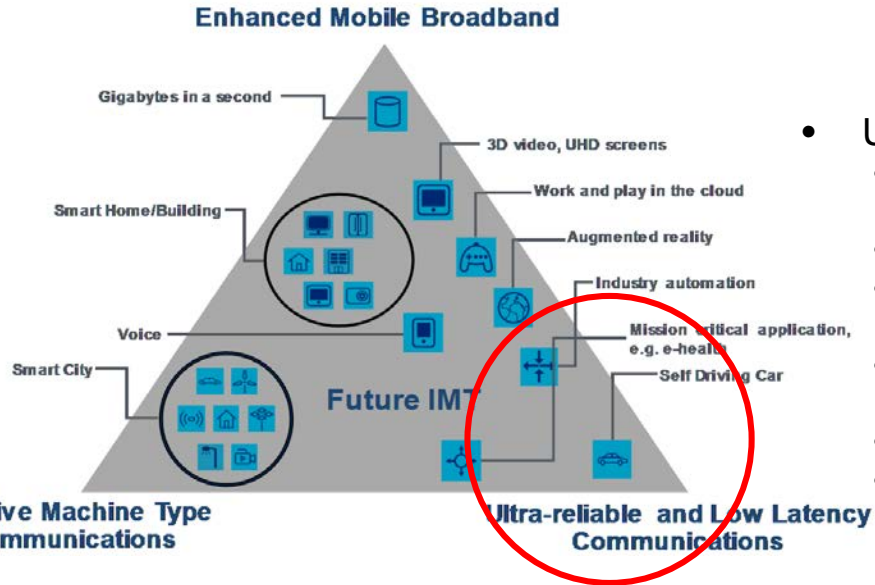
Speed & volume

Flatten total energy consumption 

Cost reduction



Source: Kanika Atri, Jan 2015



- URLLC

- Automated Traffic Control and Driving
- Collaborative Robots
- eHealth (Extreme Life Critical)
- Remote Object Manipulation (Remote Surgery)
- 3D Connectivity (Drones)
- Public Safety



End-to-end 5G reliability

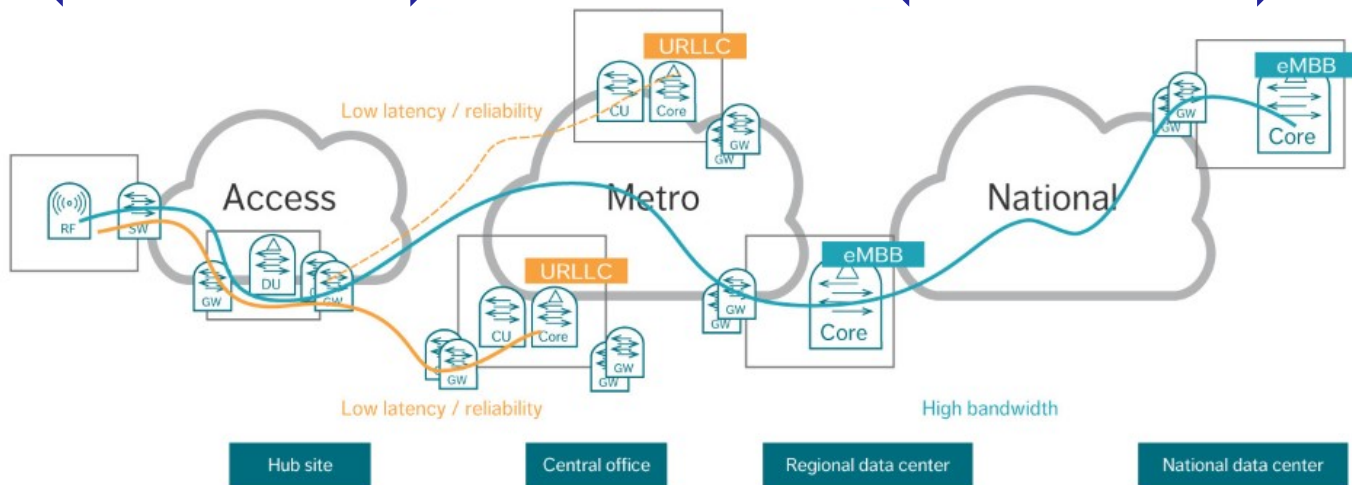
Per-segment reliability techniques

4

- Access techniques
 - packet duplication
 - massive MIMO
 - multi-connectivity (interface diversity)

Gap in research and solutions?

- Core techniques (!)
 - DRCN's bread and butter ☺
 - Protection vs. restoration
 - DPP, SBPP..
 - ...



Source: <https://www.ericsson.com/en/ericsson-technology-review/archive/2018/enabling-intelligent-transport-in-5g-networks>



- Current Radio Access Networks (RAN)
- 5G RAN:
 - **more antennas** (densification)
 - **more spectrum** (e.g., CoMP)
 - **MIMO**
 - Centralized RAN (**C-RAN**)
 - 😊 RAN coordination
 - 😞 High bandwidth
 - 😞 Low latency

A new generation of optical metro networks is needed to cope with the requirements of 5G communications



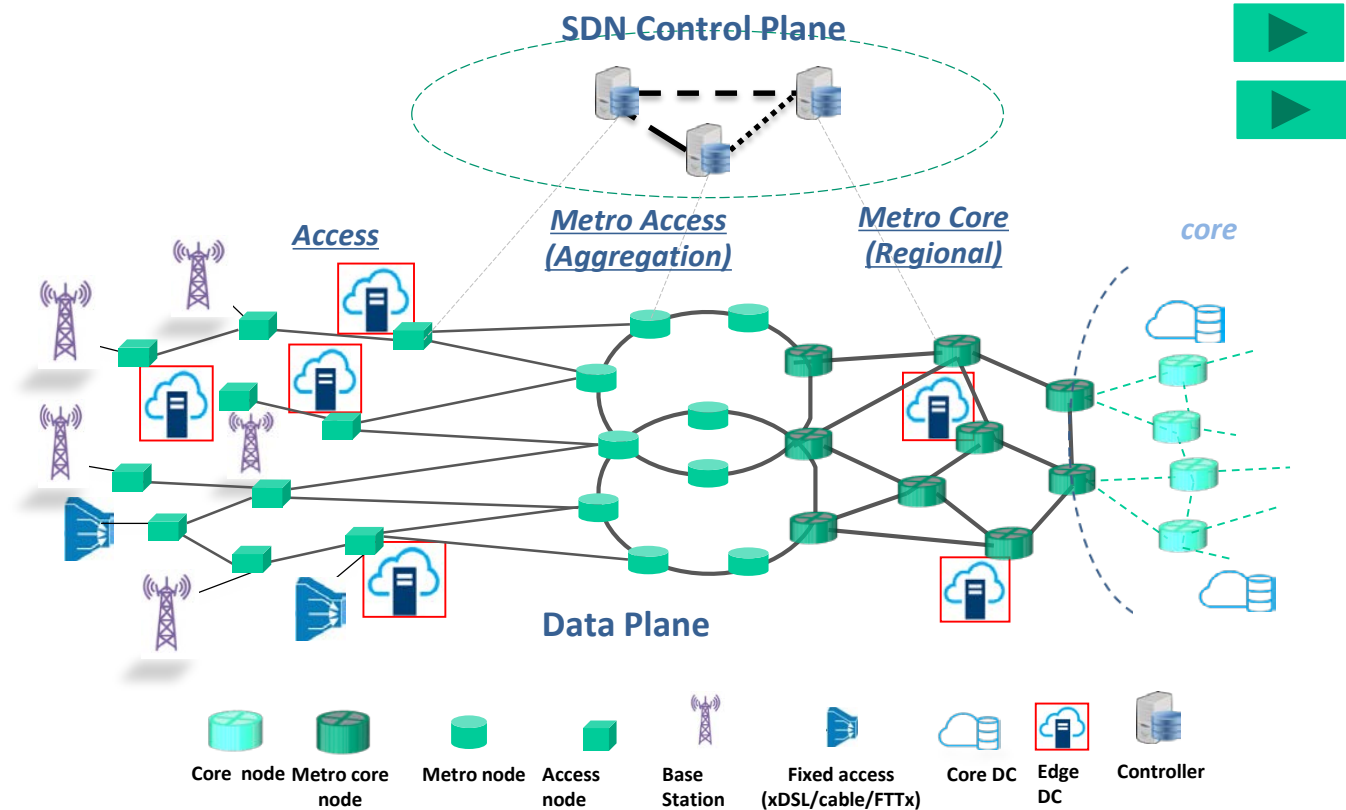
- Today
a rigid tree/ring-based aggregation infrastructure
- Tomorrow
a composite and meshed network-and-computing ecosystem



Evolution of Metro Networks (II)

Edge computing and SDN

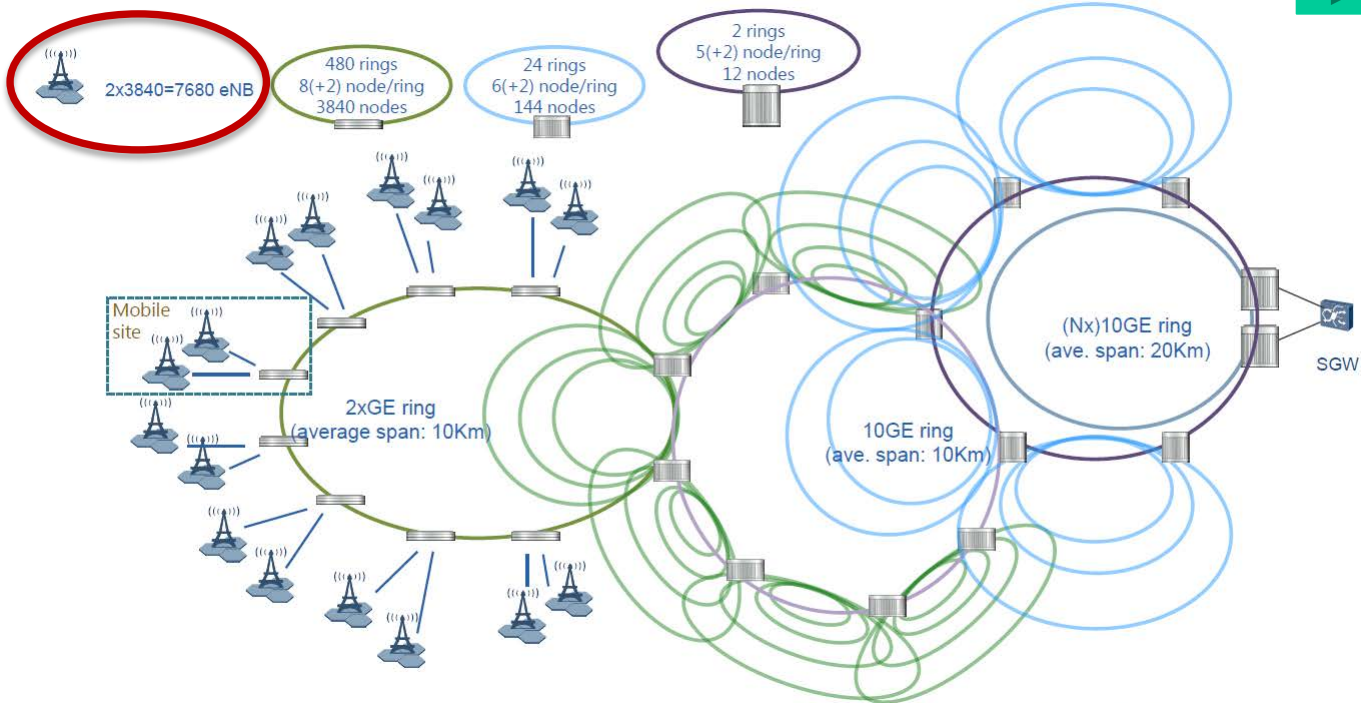
7





Well.. it looks much more like this one for a large metropolitan area...

8

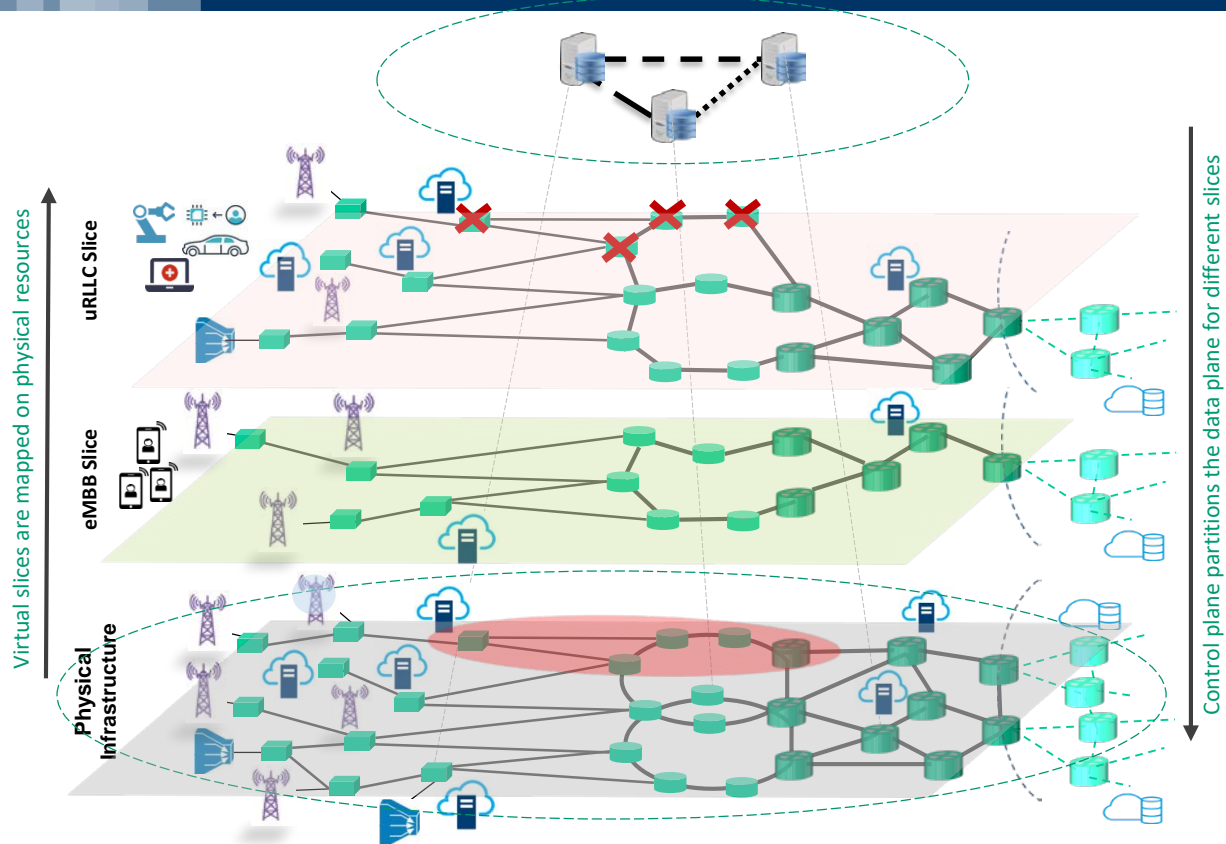




Evolution of Metro Networks (II)

Network Slicing

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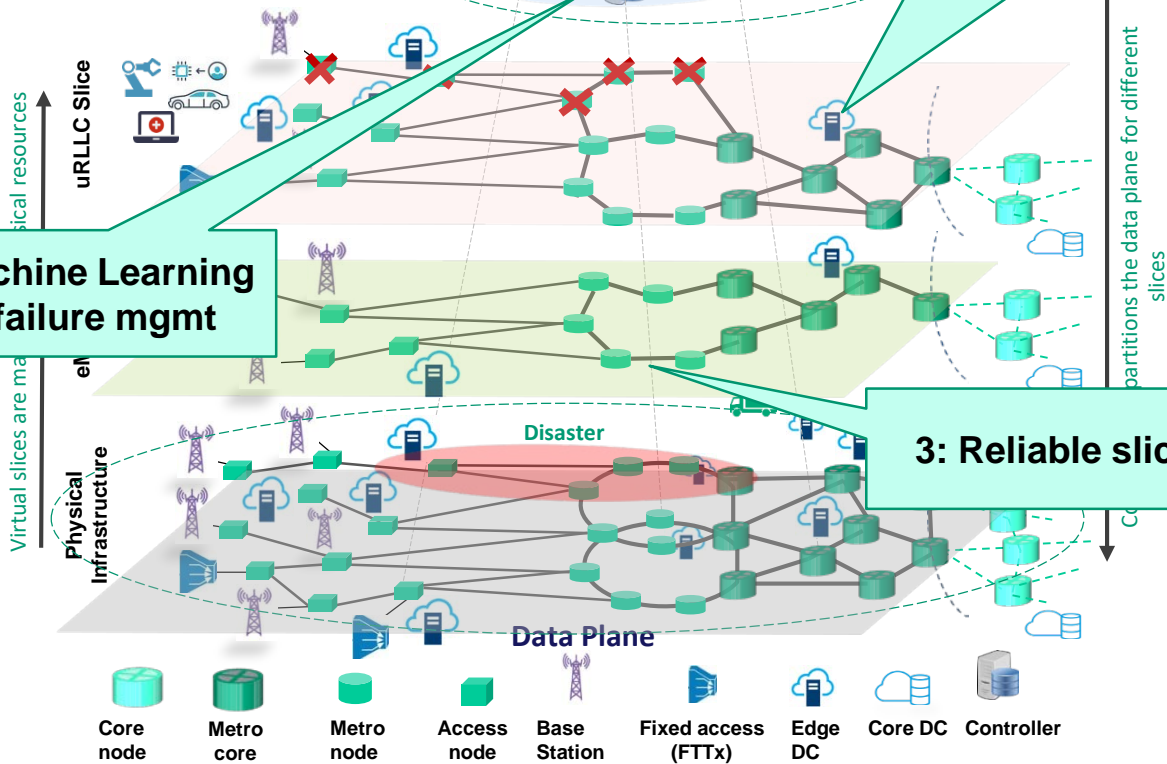
1: Resilient SDN control

SDN Control Plane

2: Content-connected slicing

4: Machine Learning for failure mgmt

3: Reliable slicing

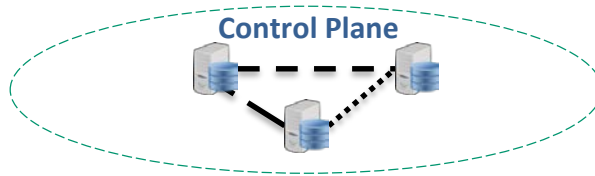




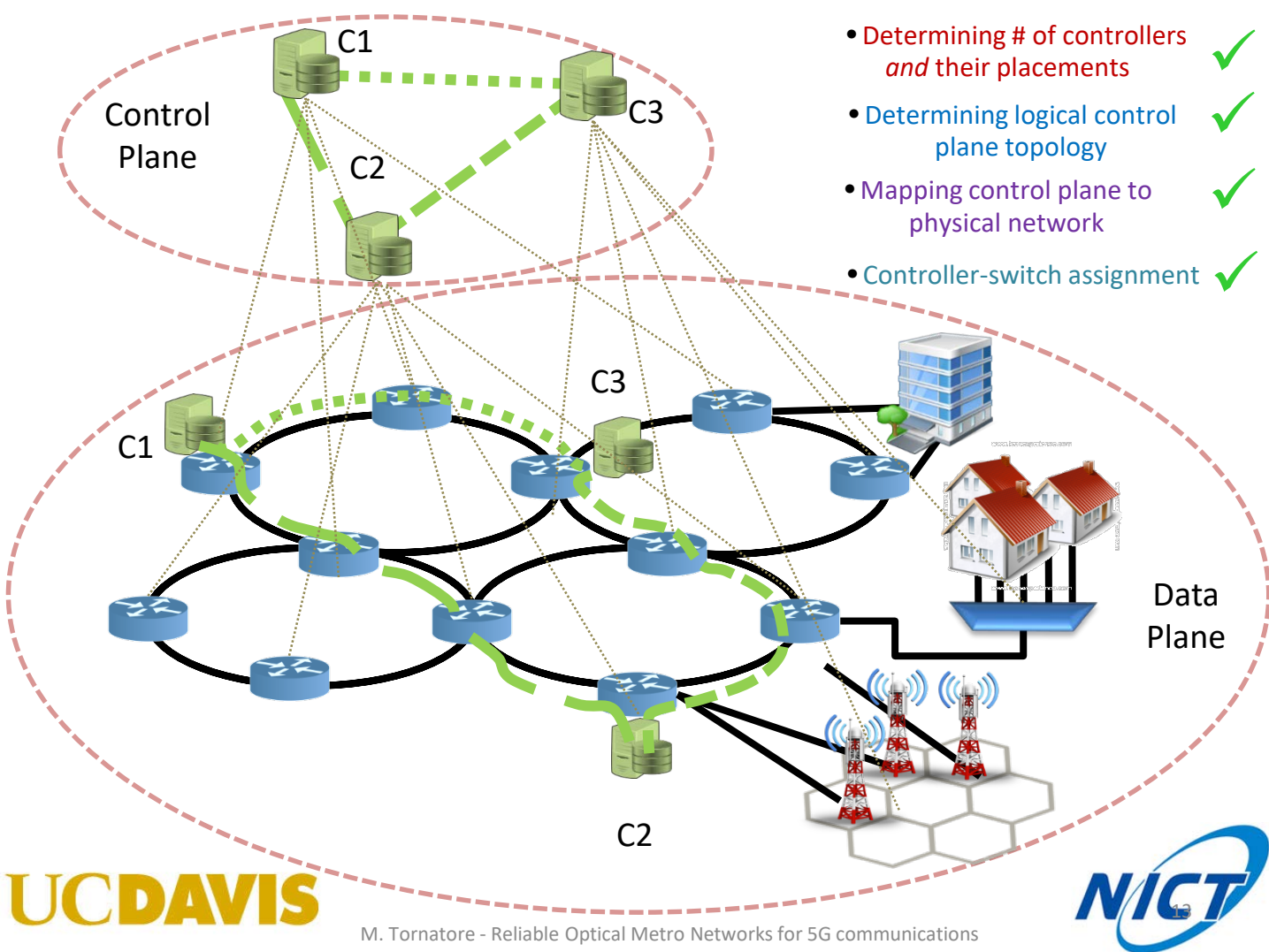
- Rising Topics
 1. **Resilient SDN control**
 2. **Content-connected slicing**
 3. **Reliable Service Chaining**
 4. **Machine Learning for failure mgmt**
- Conclusion and Future Directions



- Control plane resiliency → redundancy → distributed controllers

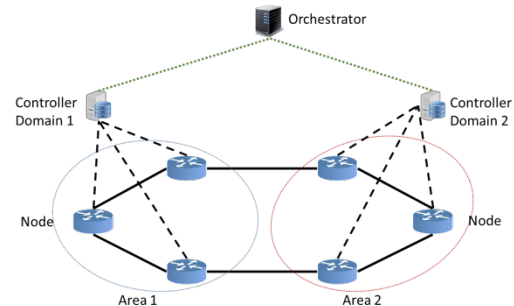


- How many controllers?*
- Where to place them?*
- Consider latency, survivability, capacity requirements, synchronization overhead, etc.*



- **CP problem (no resiliency):**

- B. Heller, et al., The controller placement problem, in: Proc. of the ACM HotSDN, New York, NY, USA, 2012.
- **[Capacitated]** G. Yao, et al., On the capacitated controller placement problem in software defined networks, IEEE Comm. Lett. 18 (8) (2014) 1339–1342.
- **[WAN]** P. Xiao, et. al, The SDN controller placement problem for WAN, in: Proc. of the IEEE/CIC ICCS, 2014.
- **[Dynamic]** M.F. Bari, et al., Dynamic controller provisioning in software defined networks, in: Proc. of the IEEE CNSM, 2013.
- **[Elastic]** A. Dixit, et. al, Towards an elastic distributed SDN controller, in: Proc. of the ACM HotSDN, New York, NY, USA, 2013.
- **[T-SDN (Orchestrator+Controllers)]** R. Lourenço, et. al, “Robust hierarchical control plane for transport software-defined networks,” Optical Switching and Networking, vol. 30, 2018



- **Fault tolerant CP problem (resiliency):**

- **[Pre-planned controller replicas]** (F.J. Ros, P.M. Ruiz, Five nines of southbound reliability in software-defined networks, in: Proc. of the ACM HotSDN, New York, NY, USA, 2014) & (B. Killi, et al., Capacitated next controller placement in software defined networks, IEEE Trans. Netw. Service Manage. 14 (3) (2017) 514–527)
- **[Path diversity]** F. Müller, et al., Survivor: an enhanced controller placement strategy for improving SDN survivability, in: Proc. of the IEEE GLOBECOM, 2014
- **[Disaster awareness]** S. Savas, et al., “Disaster-resilient control plane design and mapping in Software-Defined Networks,” *In Proc. of HPSR*, Budapest, Hungary, July 2015
- **[Malicious Attacks]** D. Santos, A. de Sousa, C.M. Machuca, Robust SDN controller placement to malicious node attacks, in: Proc. of IEEE DRCN, 2018.
- **[Several types of failures]** D. Hock, et al., Pareto-optimal resilient controller placement in SDN-based core networks, in: Proc. of the 25th International Teletraffic Congress (ITC), 2013.

- Ok controller has been properly placed...
- .. still *how we interconnect controllers to switches* is crucial to minimize recovery time!

S. Savas et. al, “RASCAR Recovery-Aware Switch-Controller Assignment and Routing in SDN”, IEEE Transactions on Network and Service Management

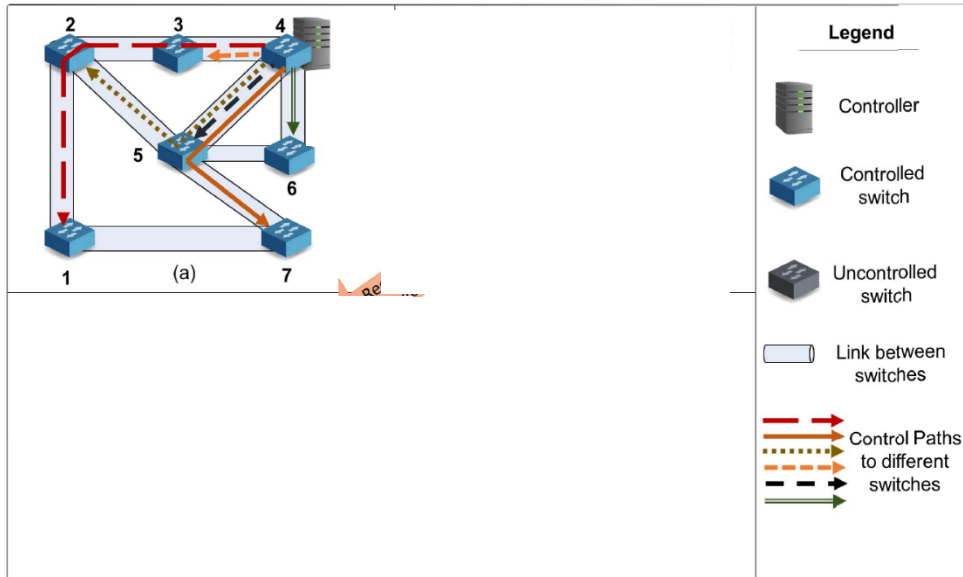


Looking at “controller to switch” paths!

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Multi-stage recovery

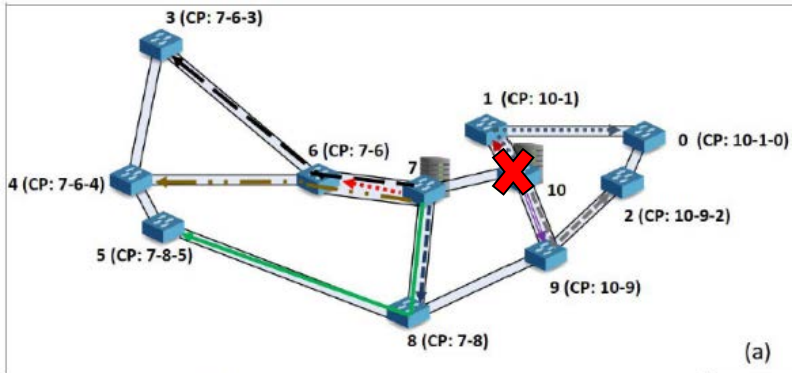
- Even a single failure affects multiple switch-to-controller **control paths**
- When switches lose control paths, they become “**uncontrolled**”:
 - route traffic using old flow entries
 - cannot exchange control messages (e.g., flow setup request, flow installation)
 - cannot be used for data path restoration



Recovery aware vs. unaware (I)

Recovery speed depends on how you route control paths

- A single failure may affect multiple switch-to-controller **control paths**.



Shortest-Path-Based Control Path Routing

0 - 1 - 10	3 - 6 - 7
1 - 10	4 - 6 - 7
2 - 9 - 10	5 - 8 - 7
9 - 10	6 - 7
	8 - 7

X → Node 10 fails.

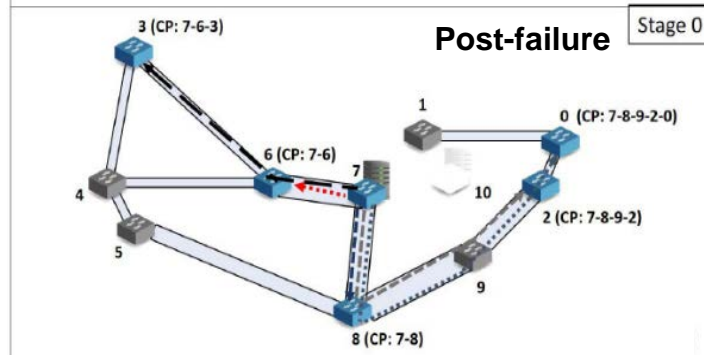
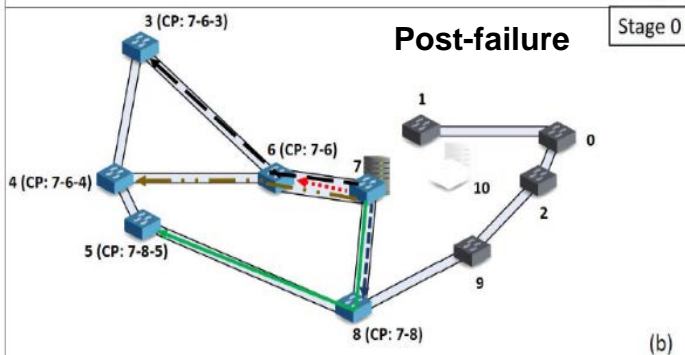
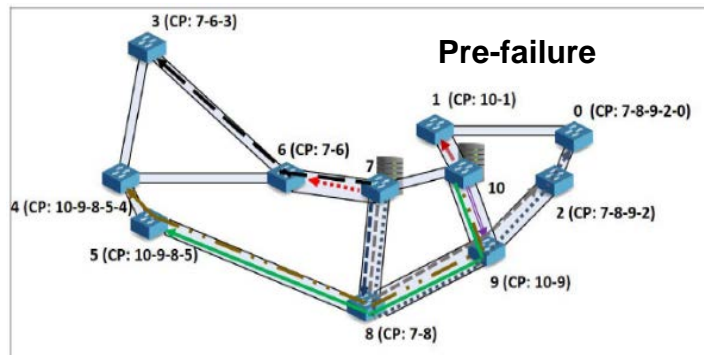
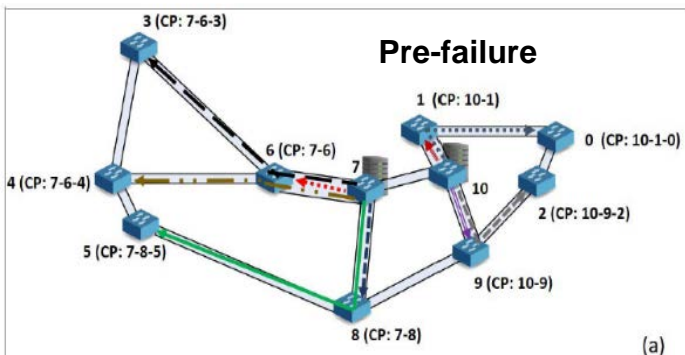
Affected control paths:

Node 0-1-2-9

● → All control is lost.

Recovery unaware → 4 recovery steps

Recovery aware → only 2 recovery steps

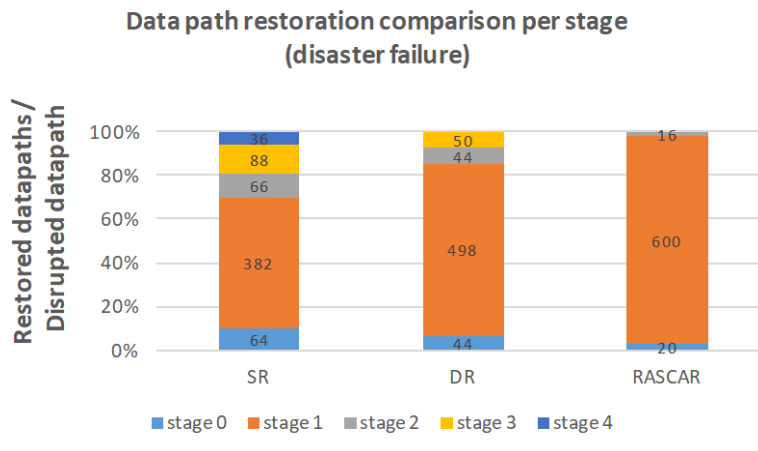
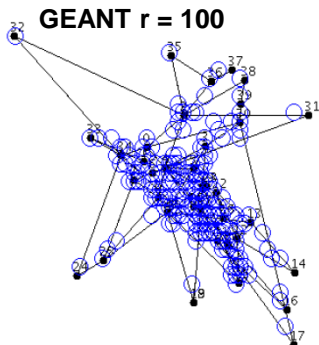


Take away: perform “load balancing” of control paths against node failures



Results: recovery speed vs. cost

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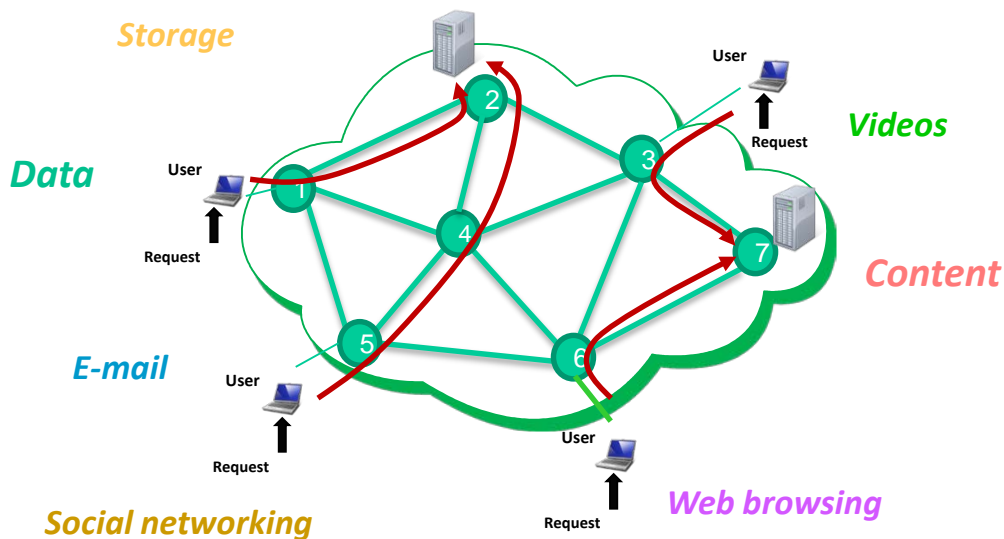


Note: what about additional cost?

Less than 1% additional resource consumption.
Only control paths become longer!



- Evolution of optical networks towards 5G
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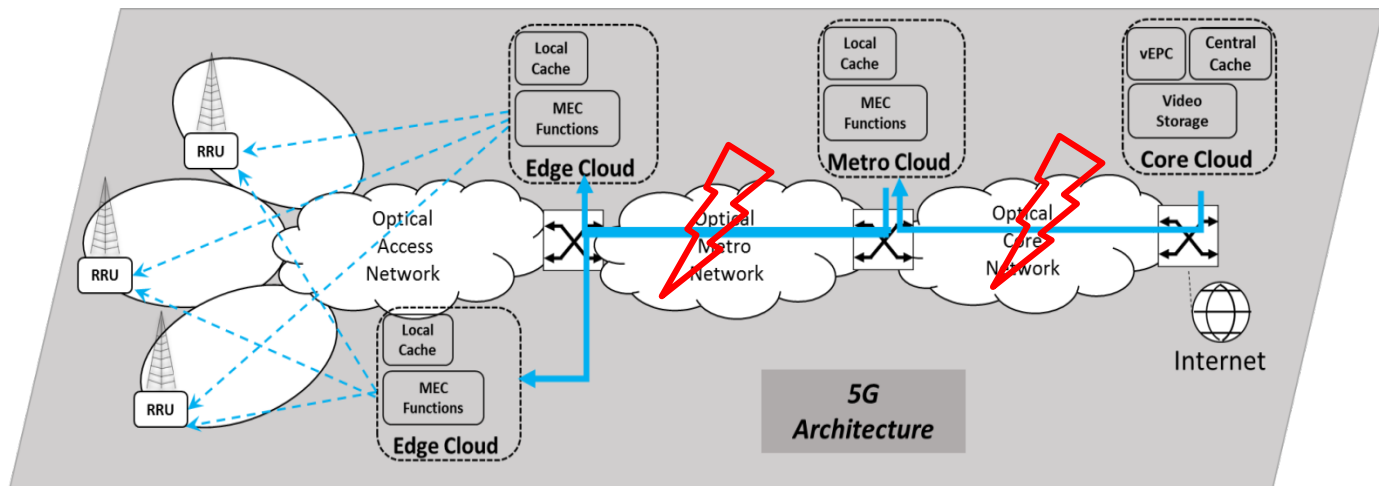
90% of the total Internet traffic is content/cloud [2]

- What really matters is the connectivity to content
- End-to-End → End-to-Content

[2] CISCO. Cisco Visual Networking Index: Forecast and Methodology, 2011-2016. in White Paper, May 2012



- 5G networks must provide 99,999% service availability [4]
 - Can we rely on a mesher network? No, costly..
 - Idea: **Alternative DCs can be accessed in case of disconnection!**
 - Enabler: Fog Computing, Mobile Edge Computing (MEC), Surrogate Servers, Caches, CORD,...
 - Latency? Traffic Offloading?.... Reliability!



[4] NGMN Alliance "5G white paper." *Next generation mobile networks, white paper* (2015).



Traditional metric:

Network connectivity (NC)

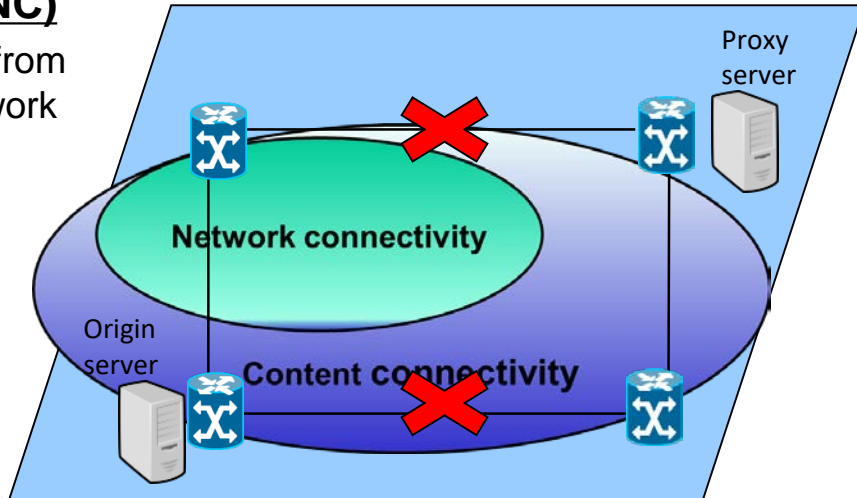
- Reachability of all nodes from any other node in the network



New metric:

Content connectivity (CC)

- Reachability of content from any node in the network

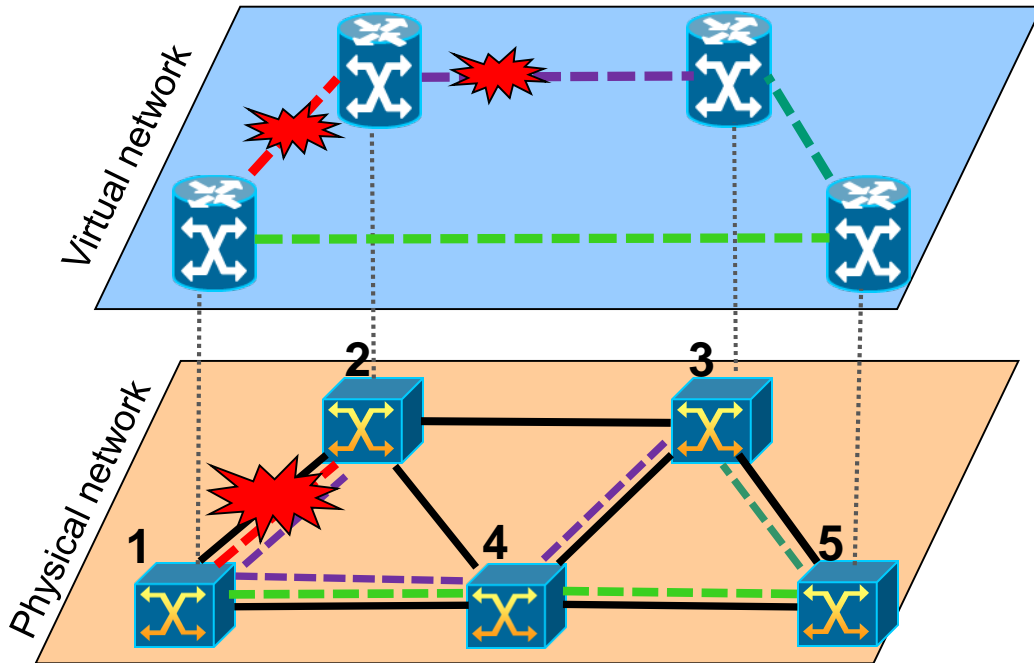




- How do survivability problems evolve in case of Content Connectivity?
- My example in the following: Survivable Virtual Network Mapping (Multi-layer protection)



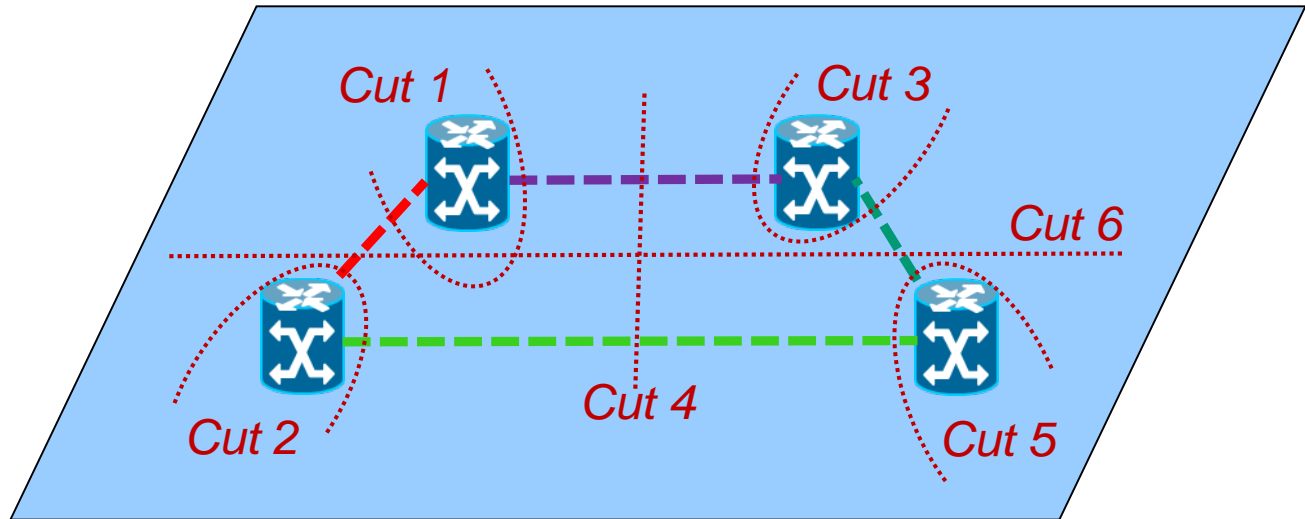
A non-survivable example



- Note: Embedding vs. Mapping



- **Cut:** set of links whose removal will partition the network into two distinct sets



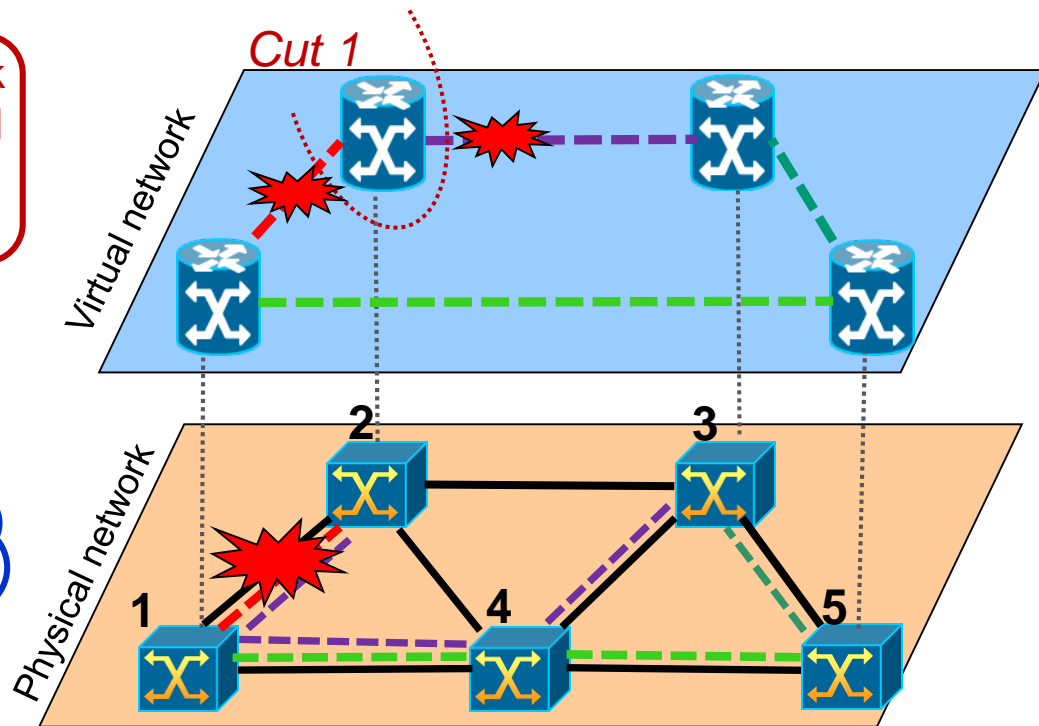
- **Condition:** no physical link shall support all the virtual links in a virtual cutset



Example



e.g., physical link
(1-2) supports all
virtual links of
Cut 1



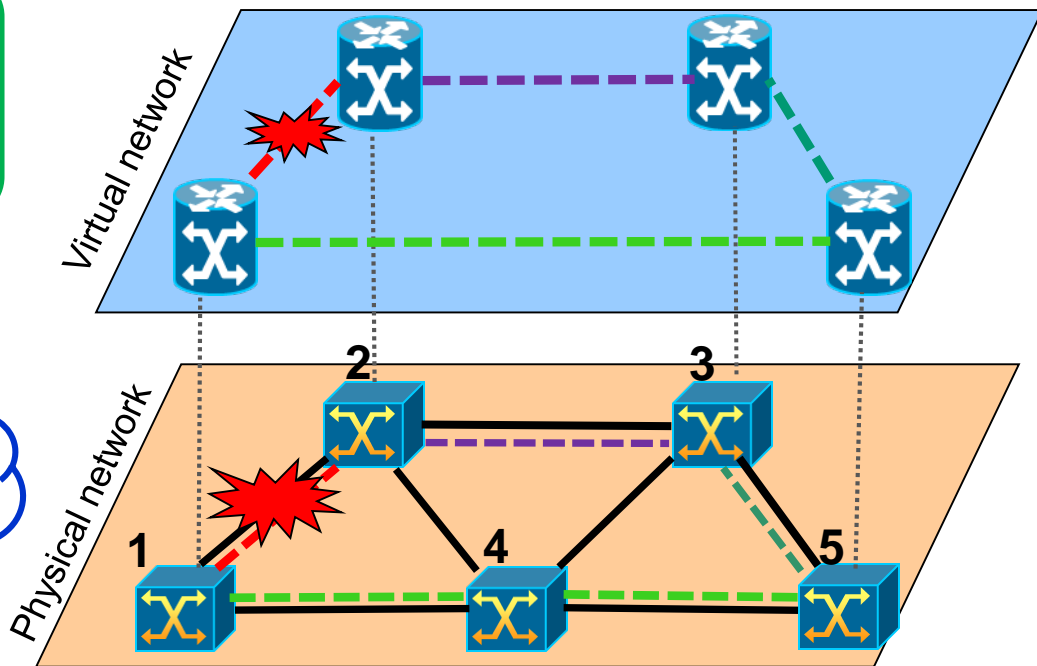
Non
Survivable
Mapping



Example

No physical link that supports all the virtual links of any cutset

Survivable Mapping





NC: no physical link shall support all the virtual links in a virtual cutset

≠

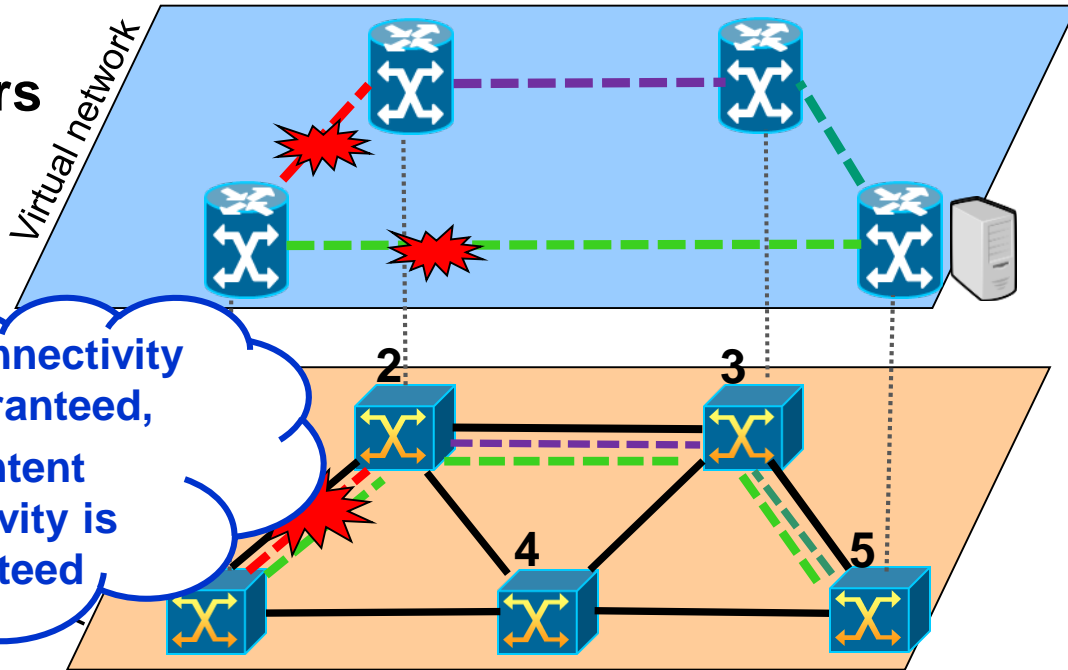
CC: all virtual nodes can reach at least one content replica after the occurrence of a failure



Scenario

1 Failure

2 Datacenters



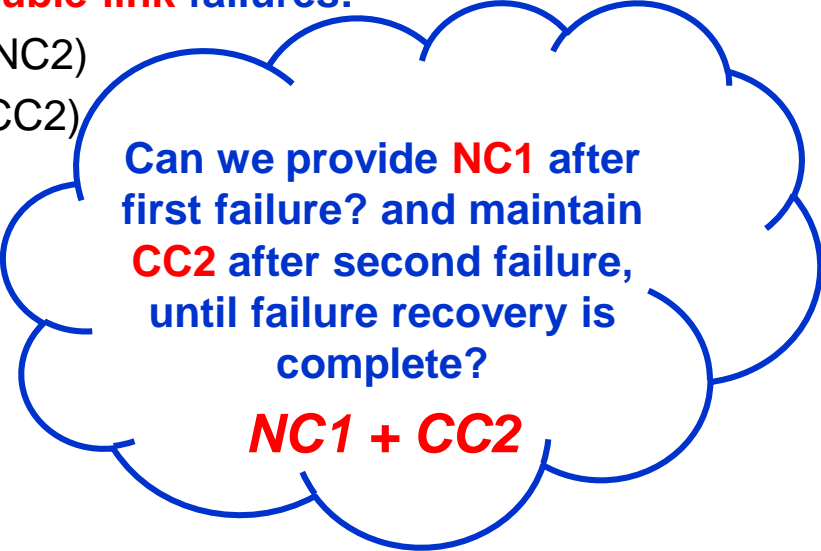


- Approaches against **single-link** failures:

- Network Connectivity (NC1)
- Content Connectivity (CC1)

- Approaches against **double-link** failures:

- Network Connectivity (NC2)
- Content Connectivity (CC2)



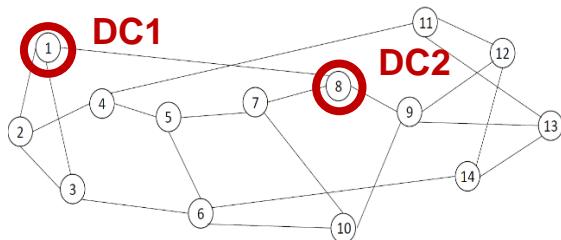
Can we provide **NC1** after first failure? and maintain **CC2** after second failure, until failure recovery is complete?

NC1 + CC2

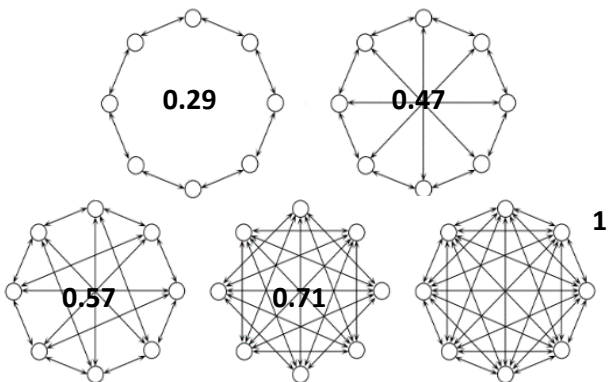


Physical topology: NSFNET

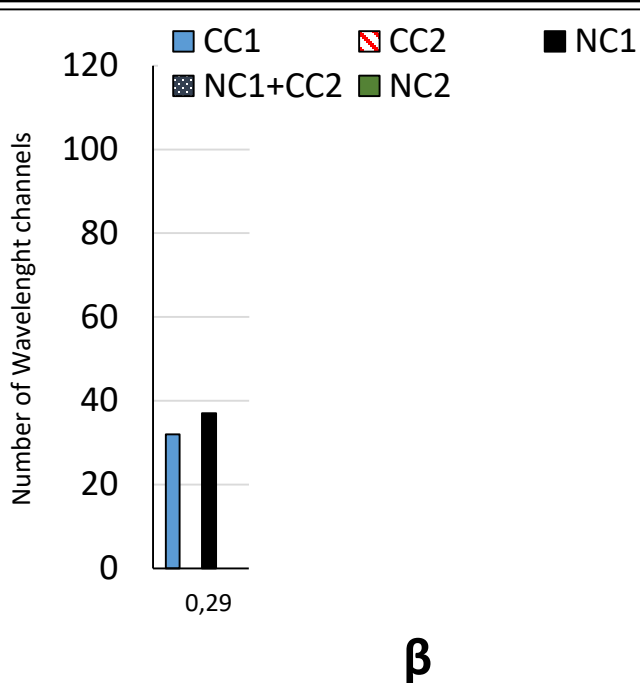
(14 nodes, 22 bidirectional links)



Logical topologies: Different connectivity degrees (β)

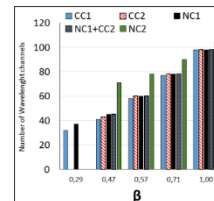
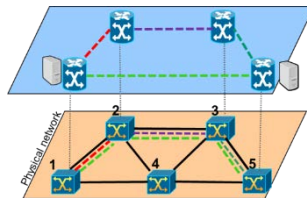


- Number of datacenters: 2
- Number of wavelengths per link: 20





- **Network connectivity for 1 failure augmented with content connectivity for two failures (NC1+CC2)** requires minimum additional resources and a limited number of datacenters
- **Several open questions, e.g.**, which strategy is better to ensure content connectivity?
 - Increase number of replicas (more datacenters)?
 - Increase connectivity of virtual network (more links)?

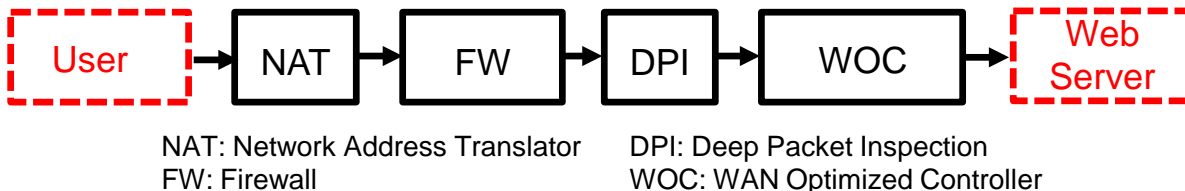




- Evolution of optical networks towards 5G
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- Slice: set of interconnected virtualized resources (net+comp) to provision a service
- Service Chain (SC): an element (one specific sequence of virtualized resources) in a slice
- Example: Web-Service SC



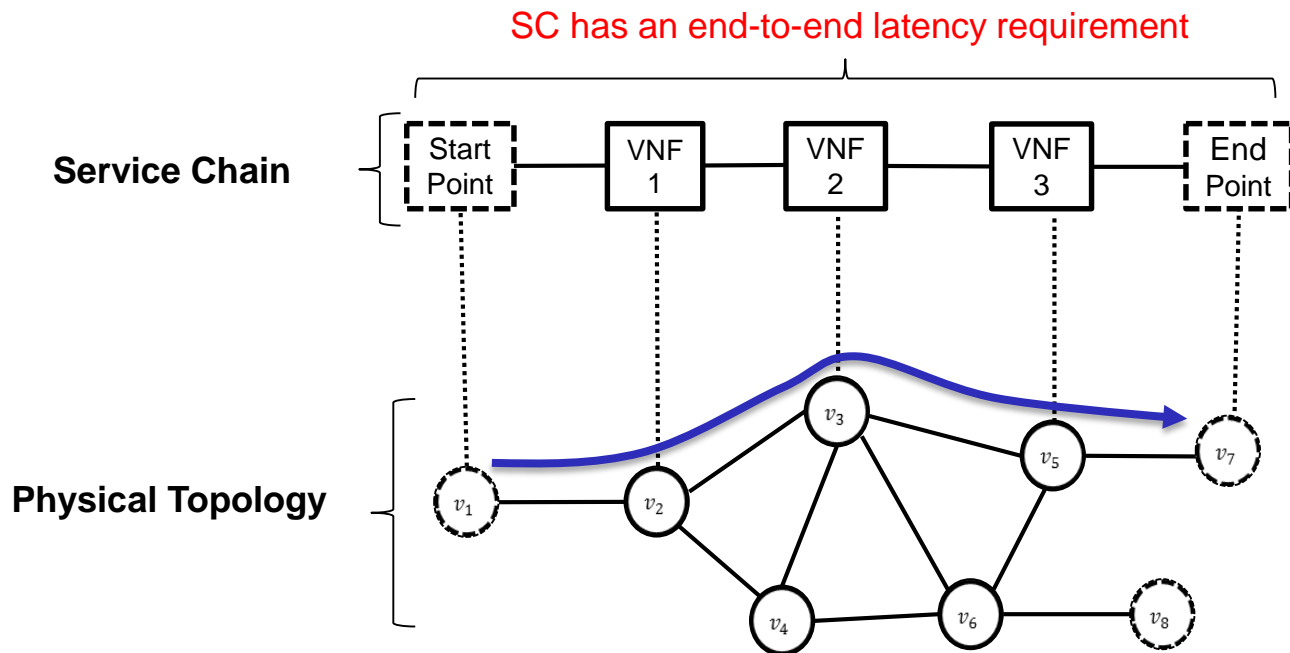
- Each SC has its own requirements in terms of
 - Bandwidth
 - Latency
 - Resiliency



Service Chaining

VNF placement + Traffic routing

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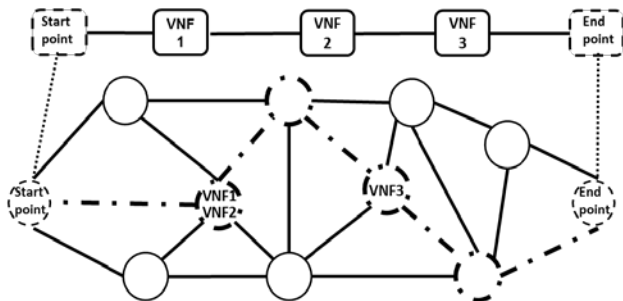




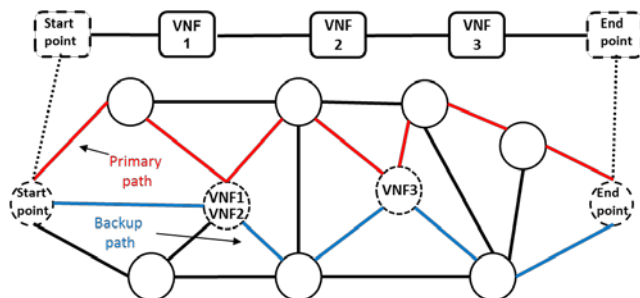
- Where do we place VNFs and route traffic to **ensure resiliency** against link/node failures?
- Which protection schemes shall we apply?



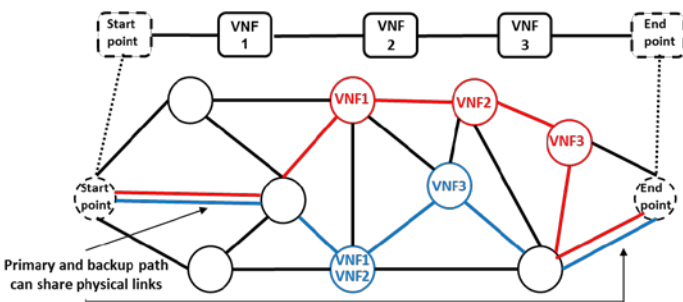
Unprotected



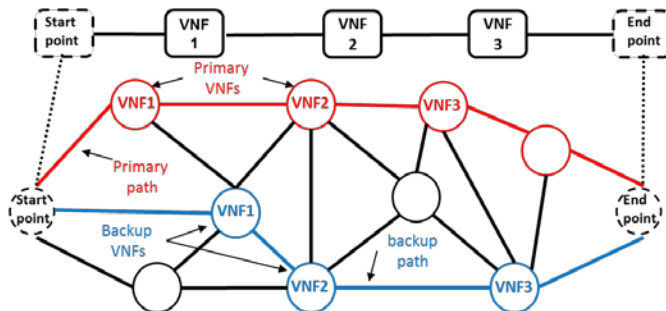
(Virtual) Link Protection (VI-P)



(Virtual) Node Protection (Vn-P)



End-to-End Protection (E2E-P)



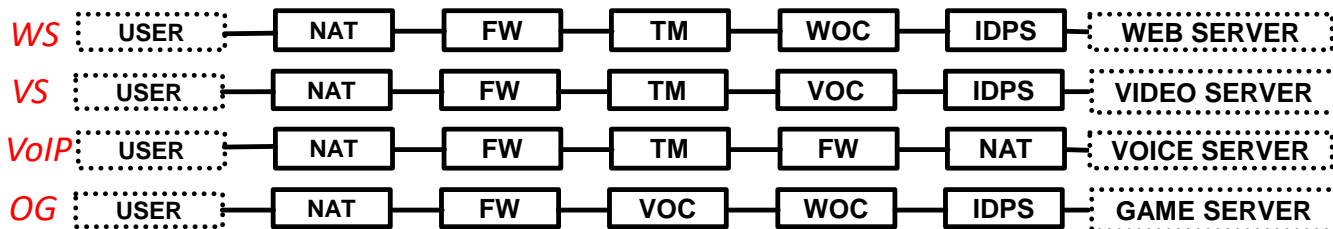
A. Hmaity et al. "Protection strategies for virtual network functions placement and service chains provisioning," *Networks*, Vol. 70, no. 4, pp. 373-387, 2017



- NSFNET network topology (14 nodes, 22 links @1Gb/s)



- 5 different types of SCs



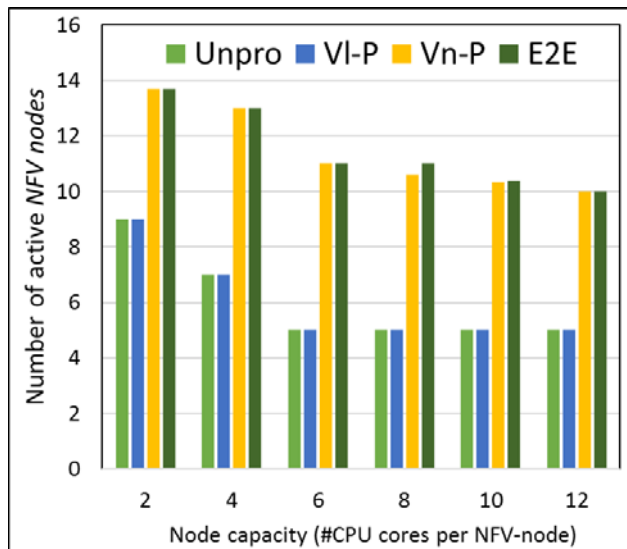
NAT: Network Address Translator, **FW:** Firewall
TM: Traffic Monitor, **VOC:** Video Optimization
Controller, **IDPS:** Intrusion Detection Prevention
System, **WOC:** WAN Optimized Controller

Service Chain	Bandwidth (kb/s)	Max latency (ms)
Web Service (WS)	100	500
Video Streaming (VS)	4000	100
VoIP	64	100
Online Gaming (OG)	50	60

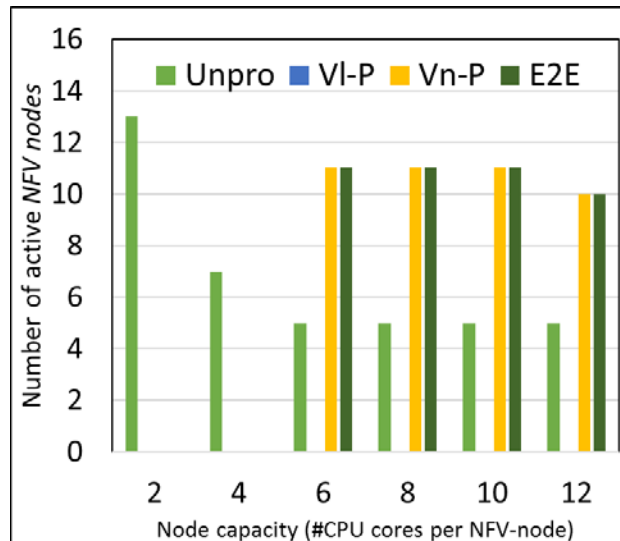
[8] M. Claypool and K. Claypool, *Latency and player actions in online games*, *Commun. ACM* 49, 11 (November 2006), 40-45
[9] A. Hmaity et al. "Virtual Network Function placement for resilient Service Chain provisioning," 2016 8th International Workshop on Resilient Networks Design and Modeling (RNDM), Halmstad, 2016, pp. 245-252.



Web Service



Online gaming



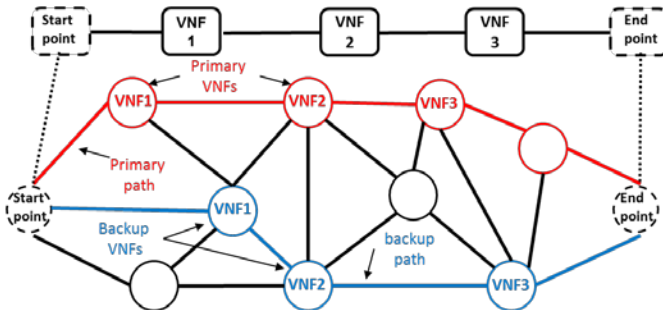


- Applications have diverse requirements (latency, computing intensity, bandwidth, reliability)
- → no one-size-fit-all protection solution
- Low-latency service are especially constrained in their protection alternatives



Jiao Zhang, et al., RABA: Resource-Aware Backup Allocation For A Chain of Virtual Network Functions

D. Chemodanov, et al., A Near Optimal Reliable Composition Approach for Geo-Distributed Latency-Sensitive Service Chains



Why «all or nothing»?

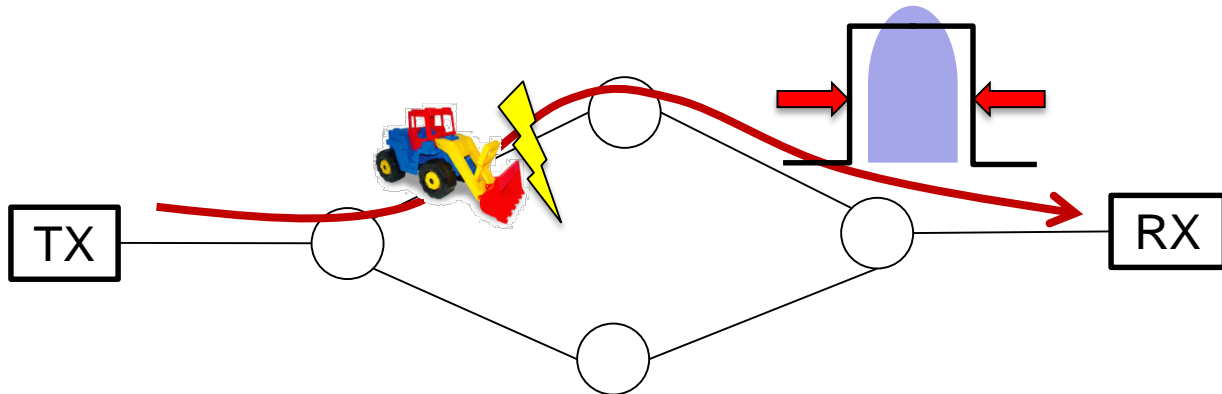
- Main research question: do we really need full (100%) replica/backup?
 - To catch an availability target, it could be enough partial protection



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- Hard-failures
 - Sudden events, e.g., fiber cuts, power outages, etc.
 - Unpredictable (? Yvan!), require «protection» (*reactive procedures*)
- Soft-failures:
 - Gradual transmission degradation due to equipment malfunctioning, filter shrinking/misalignment...
 - Trigger early network reconfiguration (*proactive procedures*)





1. Early detection (When?)

- «Predict» that BER will go above a threshold
- Allows early/quick activation of proactive procedures

2. Localization of soft-failures (Where?)

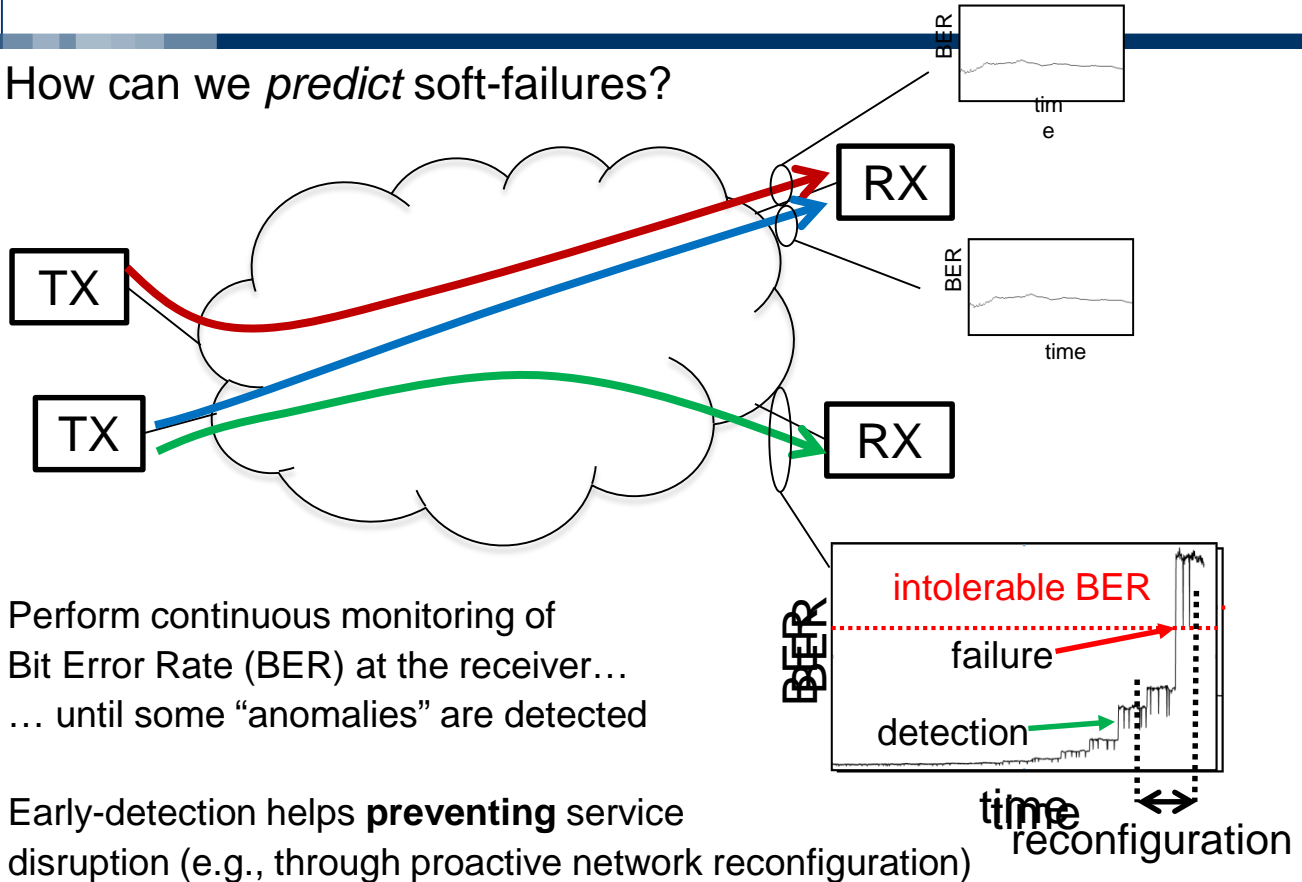
- e.g., which node/link along the path?

3. Identification (Which element?)

- e.g., filter misalignment or amplifier malfunctioning
- Reduced Time To Repair (TTR)



- How can we *predict* soft-failures?



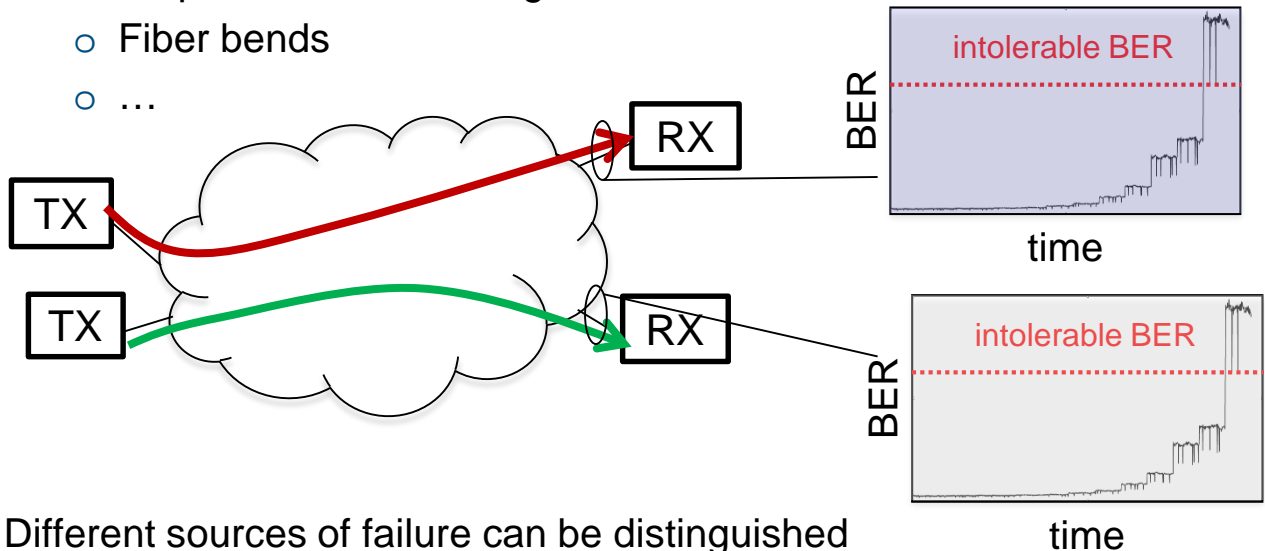


Soft-failure *identification*

Root cause analysis

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- How can we identify the *cause* of the failure?
 - Failures can be caused by different sources
 - Filters shrinking/misalignment
 - Amplifier malfunctioning
 - Fiber bends
 - ...



Different sources of failure can be distinguished via the different effects on BER (i.e., via different BER “features”)



BER monitoring and data collection

Data preprocessing

BER monitoring and data collection

Data preprocessing

BER
BER

"normal" data

anomaly

time

- Outliers removal
- Training, cross-validation and test sets formation (75% + 15% + 15% of the original data-set)

DATA RETRIEVAL

ML algorithm optimization loop

BER window formation

Features extraction

ML algorithm training

Select:

- BER sampling time (T_{BER})
- window size (duration of observation)

- BER statistics:

- mean
- min/max
- standard dev.
- Window spectral components

Fault detection:

- Binary SVM
- Random Forest
- Multiclass SVM
- Neural Network

Fault identification:

- Neural Network

Detect-Failure (DET-F)

Identify-Failure (IDENT-F)

PREDICTION & EVALUATION

TRAINING & CROSS-VALIDATION

BER

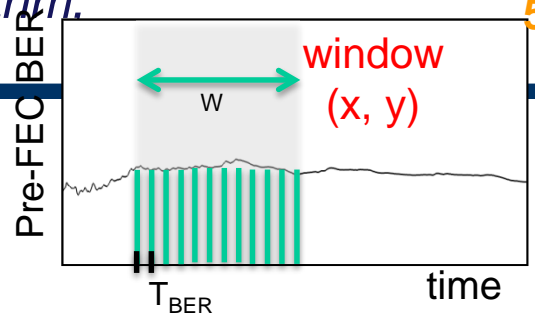
time

formation



2nd Phase: Deciding ML algorithm. Training & Validation

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1. Data Retrieval

3 decisions

Validation (optimization of hyperparameters)

BER window

- Select:
- BER sampling time (T_{BER})
 - window size (duration of observation)

Features

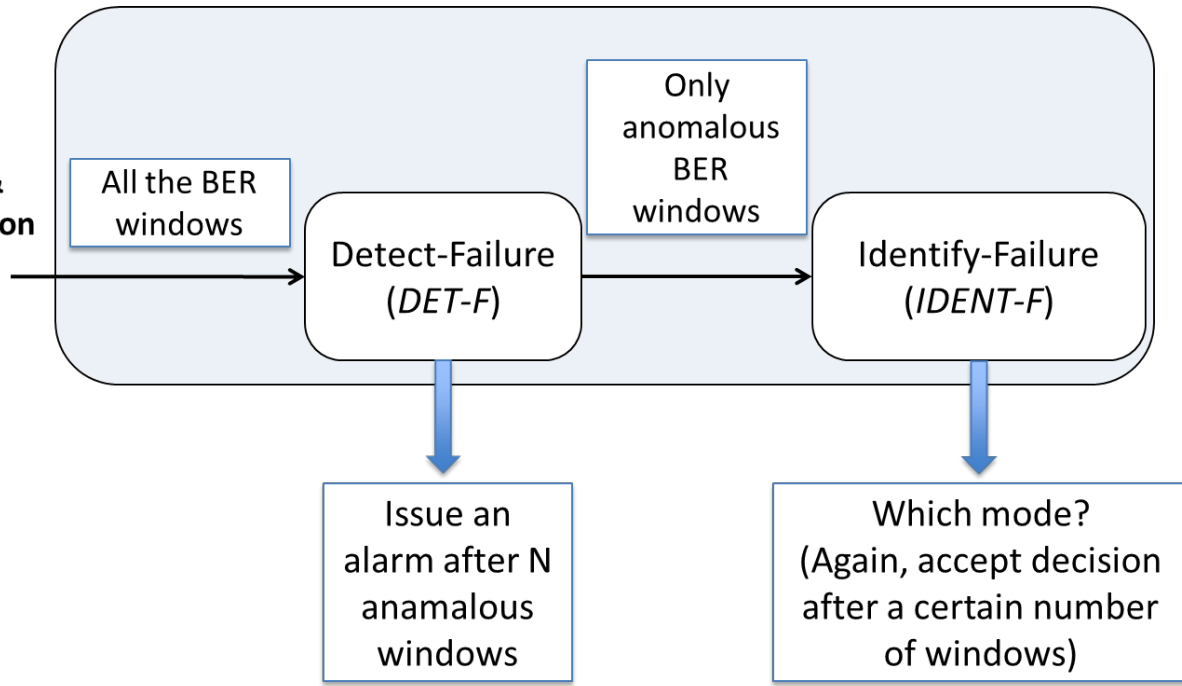
- BER statistics:
 - mean
 - min/max
 - standard dev.
- Window spectral components

ML algorithm

- Fault detection:
- Binary SVM
 - Random Forest
 - Multiclass SVM
 - Neural Network
- Fault identification:
- Neural Network

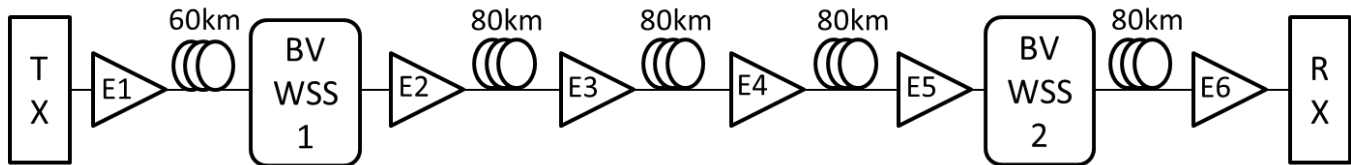
3. Prediction and Evaluation

2. Training & Cross-Validation





- Testbed for real BER traces
 - Ericsson 380 km transmission system
 - 24 hours BER monitoring
 - 3 seconds sampling interval
 - PM-QPSK modulation @ 100Gb/s
 - 6 Erbium Doped Fiber Amplifiers (EDFA) followed by Variable Optical Attenuators (VOAs)
 - Bandwidth-Variable Wavelength Selective Switch (BV-WSS) is used to emulate **2 types of BER degradation**:
 - **Filter misalignment**
 - Additional attenuation in intermediate span (e.g., due to **EDFA gain-reduction**)

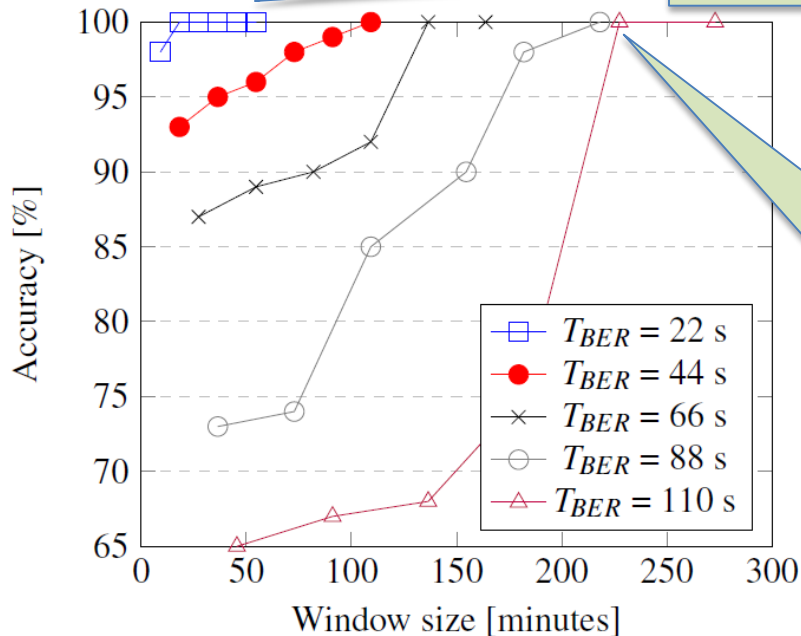




Accuracy vs window features

- Binary SVM

Take-away 1: Higher performance for with low sampling time
→ Fast monitoring equipment is required



Take-away 2: For increasing sampling time, longer “Windows” are needed for high accuracy

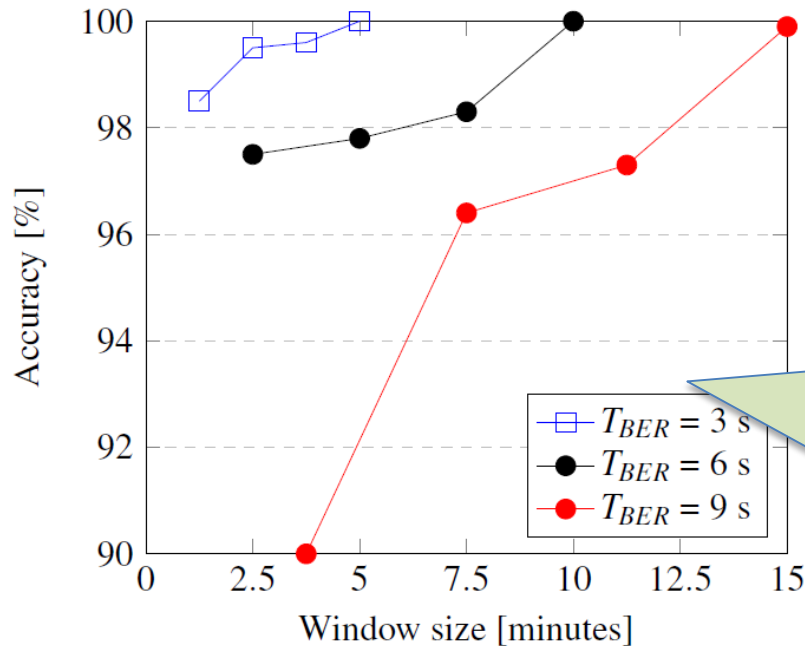


Numerical results: *Identification*

Accuracy vs window features

54

- Neural Network



Take-away 3: To perform failure-cause identification, much smaller sampling period is needed wrt failure detection



- Automated soft-failure detection and identification
 - Can reduced Time To Repair (TTR)
 - Almost instantaneous troubleshooting
 - Successful identification of root cause of failures in a controlled scenario
 - Sampling BER each few seconds led to satisfactory accuracies
 - Identification is more complex than detection (to be confirmed..)



Thank You!

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..and thanks to them!



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