

Evaluation and Design of Elastic Optical Networks Resilient to Multiple Node Failures

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Evaluation and
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RMSA problem

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Resilience

Evaluation problem

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NDC method

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Presentation Outline

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Routing, Modulation and Spectrum Assignment problem

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Work Contextualization

Consider an existing **Elastic Optical Network (EON)** with a given topology composed by **nodes** and **connecting fibers**, each fiber with a given **spectrum capacity**.

Consider an estimated set of **demands** to be supported and a **Routing, Modulation and Spectrum Assignment (RMSA)** policy adopted by the operator.

Main goals:

- Assess the multiple node failures resilience of existing EON topologies.
- Address the design problem aiming to determine a new EON maximizing the resilience metric imposed by its critical nodes.



The proposed EON problem is a **max-min-max tri-level** optimization problem:

- Compute an EON **maximizing** its evaluation value.
- The set of node failures aims to **minimize** the demand percentage that the RMSA policy is able to support.
- RMSA policy aims to **maximize** the demand percentage that is supported (by a given set of node failures).

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The **RMSA policy** rules the way lightpaths are assigned both in the regular state and in any failure state.

Consider the EON topology represented by an **undirected graph** $G = (N, E)$:

- $N = \{1, \dots, |N|\}$ – set of nodes;
- $E \subseteq \{(i, j) \in N \times N : i < j\}$ – set of links;
- $l_{ij} > 0$ – length of link $(i, j) \in E$ (in km).

$F = \{1, \dots, |F|\}$ – ordered set of **frequency slots** (FSs).

D – set of **demands** (single line rate optical network). Each $d \in D$ is defined by its source and target nodes (s_d, t_d).

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M – set of **modulation formats**. Each $m \in M$ is defined by:

- n_m – number of required contiguous FSs;
- T_m – transparent reach (in km).

P_d – set of lightpath **candidate paths** to demand $d \in D$.

Each $p \in P_d$ is defined by:

- $\alpha_{ij}^p \in \{0, 1\}$ – indicating whether link (i, j) is in p or not;
- $\beta_k^p \in \{0, 1\}$ – indicating whether node k is in p or not;
- $n_p \in \mathbb{N}$ – number of FSs required to allocate lightpath.

Optical length of p :
$$\sum_{k=1}^{n-1} \sum_{t=k+1}^n \alpha_{kt}^p l_{kt} + \Delta \left(\sum_{k=1}^n \beta_k^p - 2 \right)$$

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In this work, we consider that the **required number of FSs** n_p **depends on the candidate path** $p \in P_d$.

Moreover, for each $d \in D$, consider $n_d = \min_{p \in P_d} \{n_p\}$.

P_e – set of all candidate paths that include link $e \in E$.

$c_e = \sum_{d \in D} \sum_{p \in (P_d \cap P_e)} n_p$ – **collision metric** of link $e \in E$

$l_p = \sum_{e \in P} c_e$ – length of path $p \in \cup_{d \in D} P_d$ (according to this collision metric).

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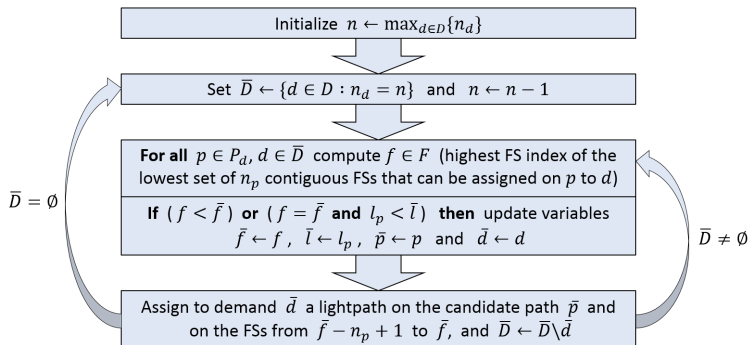
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RMSA policy (for the regular state):



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RMSA policy for the failure state is slightly different.

Lightpaths **not disrupted** by any failure node are **not changed**, *i.e.* we consider the surviving network with the FSs occupied by the non disrupted lightpaths.

For the disrupted demands whose end nodes are in the same component, a new set of candidate paths is computed.

Then, the RMSA is similar to the regular state but the demands are processed in **increasing order** of their n_d values (lightpaths requiring less number of FSs can better fit in the initial fragmented spectrum).

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Resilience Evaluation problem

The EON resilience to multiple node failures measures their impact in the network capacity to support the demands.

For a given number $c \in \mathbb{N}$ of failure nodes, we adopt a **worst-case** approach by identifying a set of c critical nodes whose simultaneous failure **maximally reduce the demand percentage** that is supported.

We solve the problem heuristically by computing 2 sets of failure nodes, running the RMSA policy for each set and **selecting the most damaging set** as the critical node set.

1. Critical Node Detection (CND) problem;
2. *Node Demand Centrality* (NDC) method.

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Critical Node Detection (CND) problem

For each node pair (i, j) consider a **weight** w_{ij} given by the sum of all demands $d \in D$ whose end-nodes are i and j .

Decision variables for optimization model:

- For each node $i \in N$,

$$v_i = \begin{cases} 1, & \text{if } i \text{ is a critical node;} \\ 0, & \text{otherwise.} \end{cases}$$

- For each node pair $i, j \in N : i < j$,

$$u_{ij} = \begin{cases} 1, & \text{if } i \text{ and } j \text{ are connected (through a path);} \\ 0, & \text{otherwise.} \end{cases}$$

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Critical Node Detection (CND) problem

Integer Linear Programming (ILP) compact model for CND problem:

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$$\min \sum_{i,j \in N: i < j} w_{ij} u_{ij} \quad (1)$$

$$\text{s.t.} \quad \sum_{i=1}^n v_i \leq c, \quad (2)$$

$$u_{ij} + v_i + v_j \geq 1, \quad (i, j) \in E, \quad (3)$$

$$u_{ij} \geq u_{ik} + u_{jk} - 1 + v_k, \quad (i, j) \notin E, \quad k \in N_{ij}, \quad (4)$$

$$v_i \in \{0, 1\}, \quad i \in N, \quad (5)$$

$$u_{ij} \in \{0, 1\}, \quad i, j \in N : i < j. \quad (6)$$

Node Demand Centrality (NDC) method

The proposed demand based centrality of each node $k \in N$ aims to **measure the impact** of the node failure on the demands between **all other node pairs**.

p_d – lightpath $p \in P_d$ assigned to demand $d \in D$.

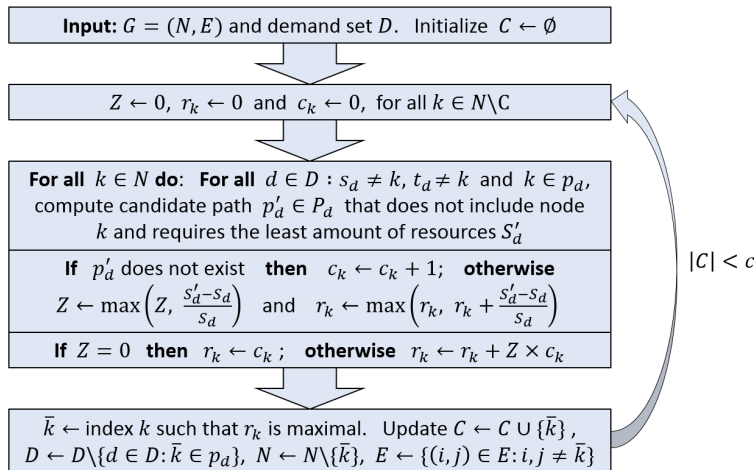
The **resources used** by each lightpath p_d , denoted as S_d , are given by its number of FSs times the number of hops of its routing path, *i.e.* $S_d = n_d \times \sum_{(i,j) \in E} \alpha_{ij}^p$.

The **node failure impact** is measured as a combination of two quantities:

1. total demand that can no longer be supported;
2. minimum resources increase required to reassign new lightpaths to demands that can be connected.



Node Demand Centrality (NDC) method



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Network Design problem

Rationale: Start with graph $G = (N, E_0)$ and randomly select one link at a time until no new link can be added within the given budget B (km).

Set of links E_0 – **Relative Neighbourhood Graph** (RNG):
 $i, j \in N$ are connected by a link if and only if there is no other node $k \in N \setminus \{i, j\}$ such that $l_{ik} \leq l_{ij}$ and $l_{jk} \leq l_{ij}$.

Define the probability $\mathbf{P}((i, j))$ of each new link (i, j) :

$$\mathbf{P}((i, j)) = \frac{1}{(|\delta_i - \delta_j| + 1) l_{ij}^2} \quad (7)$$

for all node pairs $(i, j) \notin E$ such that $l_{ij} \leq B_R$ and at least one end-node has minimum node degree.

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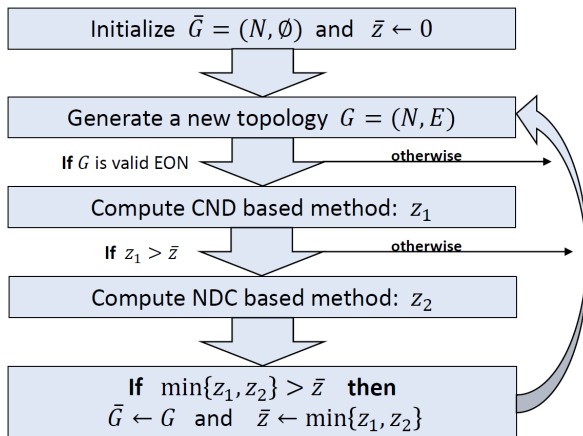
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Multi-Start Greedy Randomized algorithm:



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Parameters:

- $|F| = 320$ FSs; $c \in \{2, 3, 4, 5, 6\}$; $\Delta = 60$;
- For all $d \in D$, $|P_d| = \min\{7, \sum_{k=1}^n \beta_k^p + 1\}$, where p is the shortest path between nodes s_d and t_d .
- Modulation format configurations:

m	n_m	T_m (km)
1	1	500
2	2	1250
3	3	2000
4	4	2500

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Topology characteristics of each tested network:

Network	$ N $	$ E $	Pairs	$\bar{\delta}$	2-C	L	Diameter
Germany50	50	88	1225	3.52	Yes	8859	1417
PalmettoNet	45	64	990	2.84	No	4286	1298
MissouriNA	64	80	2016	2.50	No	4001	1301

Regarding the set of demands D , we consider:

- 4 sets for Germany50, with increasing number of demands (Ger_a, Ger_b, Ger_c, Ger_d);
- 2 sets for both PalmettoNet (Pal_a, Pal_b) and MissouriNA (Mis_a, Mis_b).

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Resilience evaluation of existing networks

Instance	RMSA t(s)	c	CND method		NDC method	
			Value	t(s)	Value	t(s)
Ger_a	23	2	0.8433	2	0.8283	12
		3	0.5750	1	0.5750	4
		4	0.5200	2	0.5200	4
		5	0.4050	3	0.4983	5
		6	0.3350	3	0.4683	9
Ger_b	50	2	0.8457	4	0.7380	22
		3	0.5804	2	0.5804	5
		4	0.5224	3	0.5224	6
		5	0.4049	5	0.5004	7
		6	0.3388	6	0.4727	13
Ger_c	51	2	0.8257	3	0.7236	23
		3	0.5878	2	0.5878	5
		4	0.5345	3	0.5345	6
		5	0.4128	4	0.5088	12
		6	0.3453	5	0.4149	8
Ger_d	52	2	0.8128	3	0.7119	23
		3	0.5930	2	0.5930	5
		4	0.5252	7	0.5426	6
		5	0.4186	5	0.5084	12
		6	0.3357	4	0.4284	9



Resilience evaluation of existing networks

Instance	RMSA t(s)	c	CND method		NDC method	
			Value	t(s)	Value	t(s)
Pal_a	19	2	0.5165	1	0.5496	2
		3	0.3430	1	0.4587	3
		4	0.2769	1	0.2851	3
		5	0.1653	1	0.2190	3
		6	0.1116	1	0.1632	4
Pal_b	24	2	0.5161	1	0.5528	2
		3	0.3492	1	0.4594	3
		4	0.2833	1	0.2925	3
		5	0.1730	1	0.2266	4
		6	0.1194	1	0.1715	4
Mis_a	51	2	0.4657	2	0.8770	8
		3	0.2964	2	0.6694	17
		4	0.2218	2	0.3327	11
		5	0.1593	2	0.2581	12
		6	0.1169	2	0.1734	12
Mis_b	69	2	0.4598	3	0.8720	9
		3	0.3140	3	0.6592	18
		4	0.2366	3	0.4271	12
		5	0.1652	3	0.2470	11
		6	0.1265	3	0.1786	12



Network Design - Generation and Validation

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Instance	Valid EONs	Time (hh:mm:ss)		
		Generation	Topology Val.	RMSA Val.
Ger_a	929	00:00:01	00:00:48	06:52:47
Ger_b	676	00:00:01	00:00:47	14:02:58
Ger_c	260	00:00:01	00:00:46	14:09:54
Ger_d	23	00:00:01	00:00:46	14:20:49
Pal_a	1000	00:00:01	00:00:01	04:52:14
Pal_b	999	00:00:01	00:00:01	07:10:13
Mis_a	1000	00:00:01	00:00:01	12:16:21
Mis_b	1000	00:00:01	00:00:01	18:41:03

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Instance	c	Original	Best	Time (hh:mm:ss)
Ger_a	2	0.8283	0.9200	00:51:53
	3	0.5750	0.8067	00:51:07
	4	0.5200	0.6517	00:51:14
	5	0.4050	0.5150	00:48:57
	6	0.3350	0.4217	00:45:04
Ger_b	2	0.7380	0.8824	01:17:15
	3	0.5804	0.7624	01:17:22
	4	0.5224	0.6490	01:14:25
	5	0.4049	0.5224	01:11:58
	6	0.3388	0.4171	01:01:32
Ger_c	2	0.7236	0.8588	00:27:55
	3	0.5878	0.7500	00:31:41
	4	0.5345	0.6466	00:32:11
	5	0.4128	0.5162	00:30:02
	6	0.3453	0.4135	00:25:48
Ger_d	2	0.7119	0.8191	00:04:18
	3	0.5930	0.7246	00:03:47
	4	0.5252	0.6214	00:05:32
	5	0.4186	0.5142	00:04:04
	6	0.3357	0.3878	00:03:23

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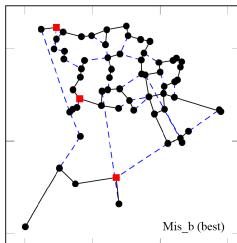
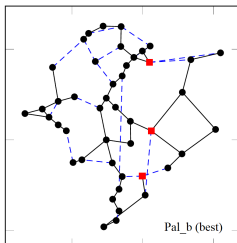
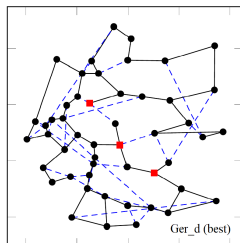
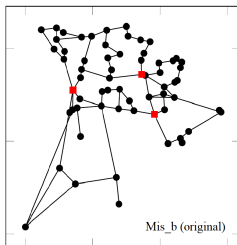
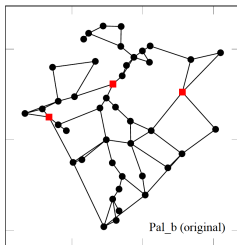
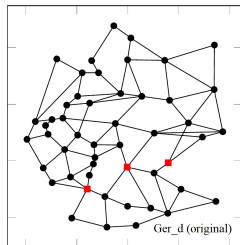
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Instance	c	Original	Best	Time (hh:mm:ss)
Pal_a	2	0.5165	0.8306	00:30:37
	3	0.3430	0.6488	00:28:59
	4	0.2769	0.4855	00:27:55
	5	0.1653	0.3533	00:22:56
	6	0.1116	0.2438	00:19:50
Pal_b	2	0.5161	0.8300	00:37:15
	3	0.3492	0.6493	00:33:26
	4	0.2833	0.4855	00:32:44
	5	0.1730	0.3553	00:26:36
	6	0.1194	0.2466	00:22:32
Mis_a	2	0.4657	0.8226	01:10:41
	3	0.2964	0.6935	01:40:11
	4	0.2218	0.5242	01:06:44
	5	0.1593	0.3992	01:05:17
	6	0.1169	0.3105	01:00:55
Mis_b	2	0.4598	0.8229	01:29:37
	3	0.3140	0.6979	02:03:13
	4	0.2366	0.5298	01:17:20
	5	0.1652	0.4033	01:17:49
	6	0.1265	0.3170	01:13:04

Original topologies and Best topologies



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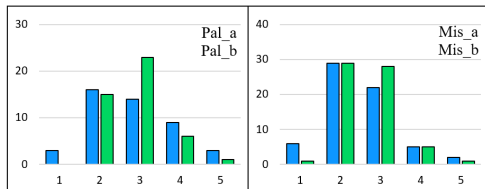
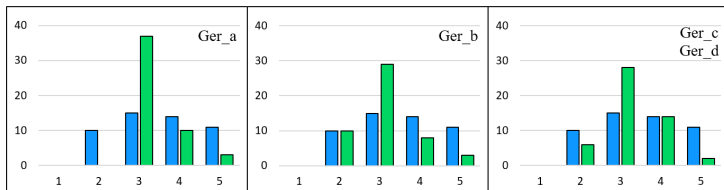
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- In this work, we have considered the evaluation and network design of EONs resilient to multiple node failures.
- First, we have addressed the resilience of EONs to multiple node failures by identifying the critical nodes whose simultaneous failure maximally reduce the demand percentage that is supported by the network.
- Second, we have addressed the design of a new EON maximizing the resilience metric imposed by its critical nodes.
- The results showed that EONs resilient to multiple node failures have topologies with more homogeneous node degrees which are very different from the original ones.



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